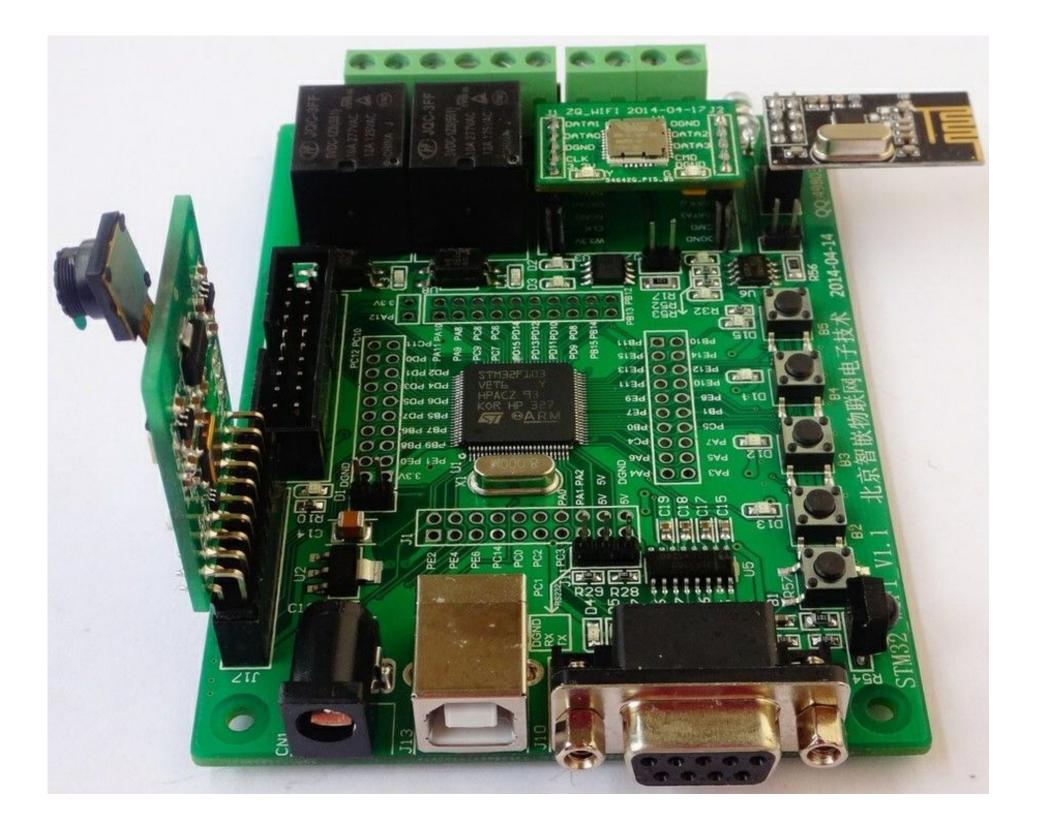




SOW III Let's Solve It





@MaciekGajdzica ucgosu.pl



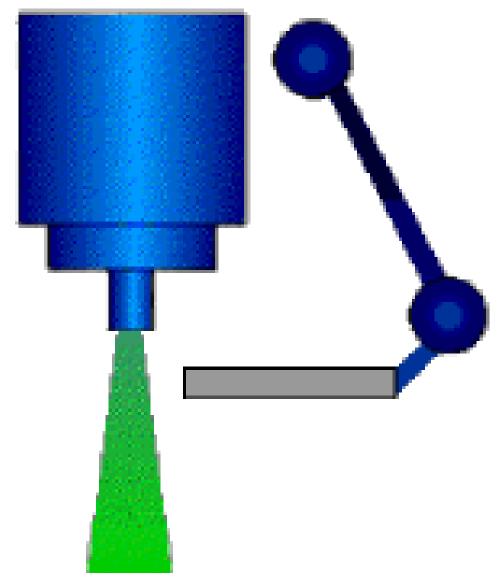
"Will we continue on our undisciplined course, blown by the chaotic winds of business and government, until one of us finally blunders badly enough to wake the sleeping giant of government regulation?"

ROBERT C. MARTIN



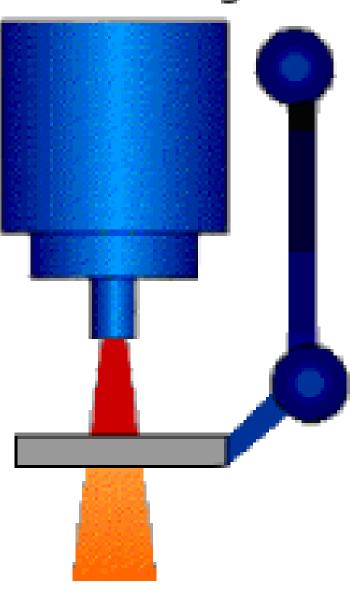


low current electron beam was scanned across the field



Electron Mode

high current electron beam was tracked at the target



X-Ray Mode

high current electron beam with no target > 'lightning' THE PROBLEM

tray including the target, a flattening filter, the collimator jaws and an ion chamber was moved OUT for "electron" mode, and IN for "photon" mode.

THERAC-25

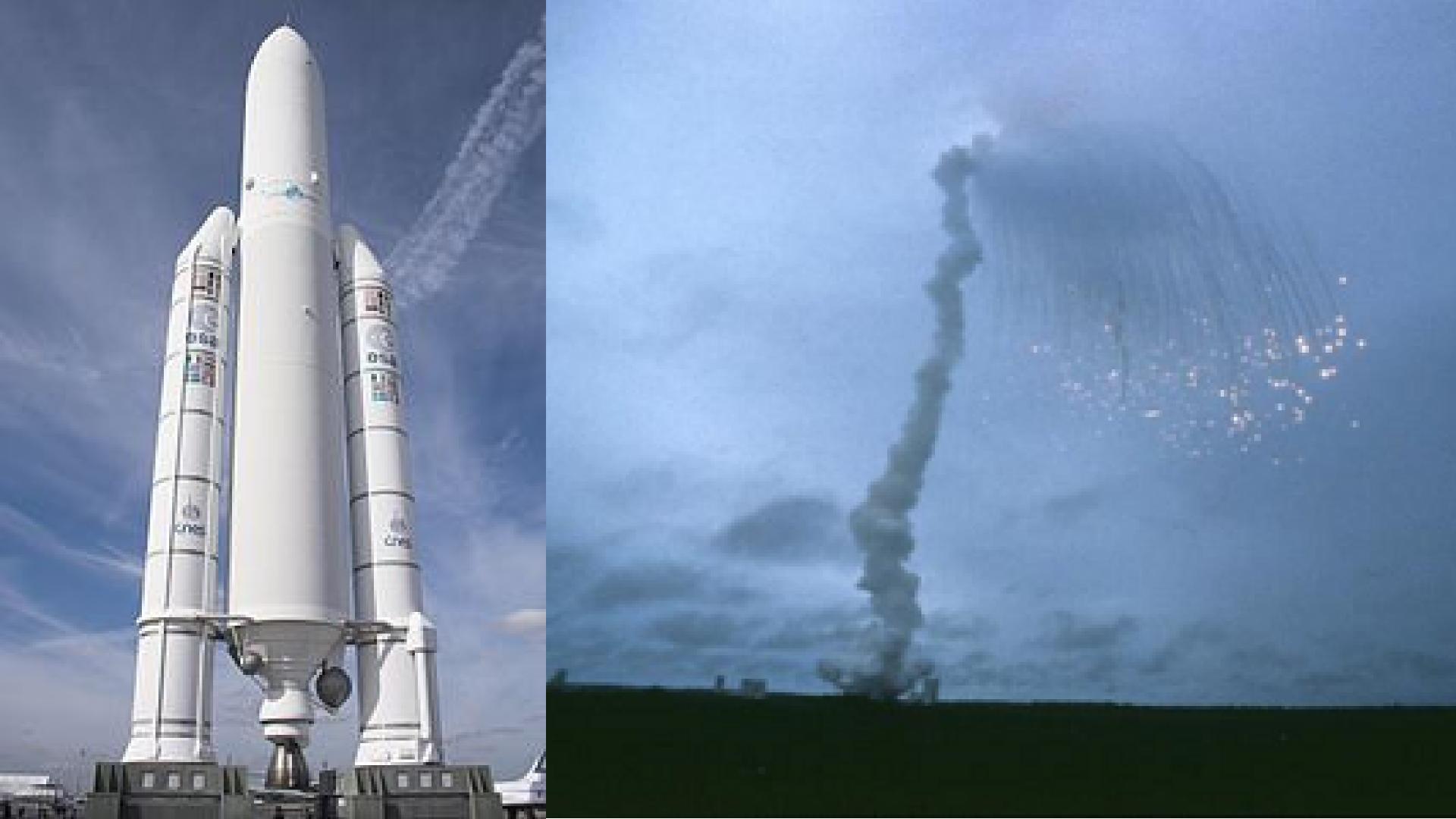
```
if mode/energy specified then
   begin
      calculate table index
      repeat
         fetch parameter
          output parameter
          point to next parameter
      until all parameters set
      call Magnet
      if mode/energy changed then return
   end
if data entry is complete then set Tphase to 3
if data entry is not complete then
   if reset command entered then set Tphase to 0
return
```

```
Magnet:
      Set bending magnet flag
      repeat
          Set next magnet
          call Ptime
          if mode/energy has changed, then exit
      until all magnets are set
      return
Ptime:
      repeat
          if bending magnet flag is set then
             if editing taking place then
                if mode/energy has changed then exit
      until hysteresis delay has expired
      Clear bending magnet flag
```

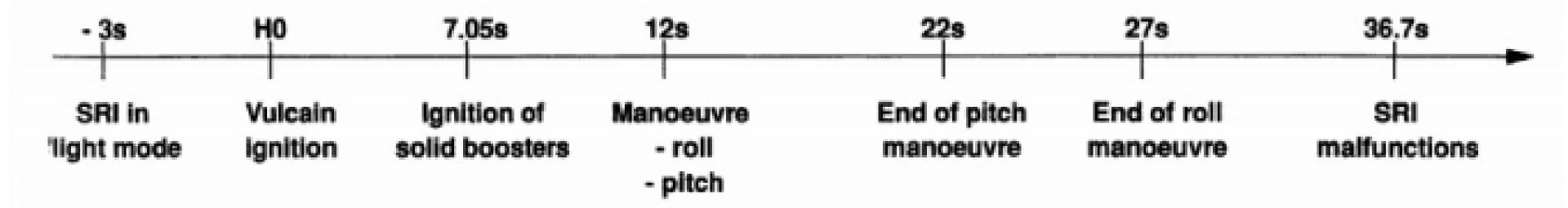
return

THERAC-25

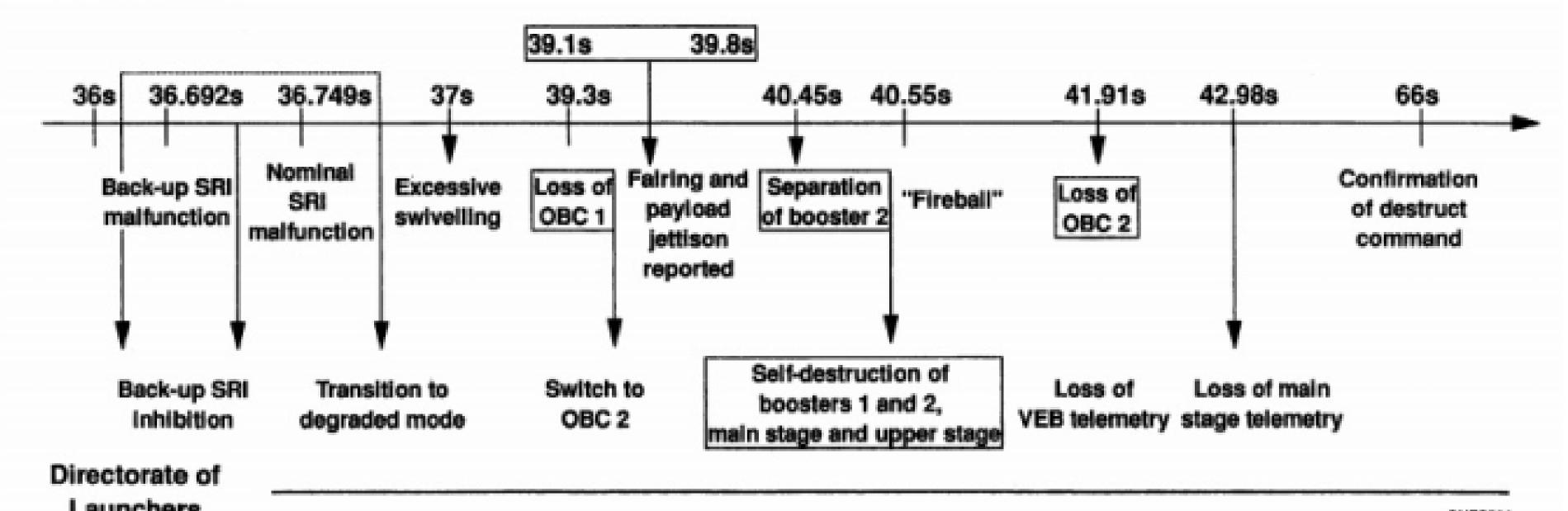
- Whole program implemented by a single person
- No documentation
- Faulty risk assessment
- Insufficient tests
- Ignoring reported issues



Nominal flight



Accident



Why visibility matters—the Ariane 5 crash

- Velocity was represented as a 64-bit floor
- A conversion into a 16bit signed integer caused an overflow
- The current velocity of Ariane 5 was too high to be represented as a 16-bit integer
- Error handling was suppressed for performance reasons

```
-- Vertical velocity bias as measured by sensor
L M BV 32:=
  TBD.T_ENTIER_32S ((1.0/C_M_LSB_BV) *
  G M INFO DERIVE(T ALG.E BV));
-- Check, if measured vertical velocity bias ban be
-- converted to a 16 bit int. If so, then convert
if L M BV 32 > 32767 then
  P M DERIVE(T ALG.E BV) := 16#7FFF#;
elsif L M BV 32 < -32768 then
  P_M_DERIVE(T_ALG.E_BV) := 16#8000#;
else
  P_M_DERIVE(T_ALG.E_BV) :=
          UC_16S_EN_16NS(TDB.T_ENTIER_16S(L_M_BV_32));
end if:
-- Horizontal velocity bias as measured by sensor
-- is converted to a 16 bit int without checking
P M DERIVE(T ALG.E BH) :=
  UC 16S EN 16NS (TDB.T ENTIER 16S ((1.0/C M LSB BH) *
  G_M_INFO_DERIVE(T_ALG.E_BH)));
```

*Source: http://moscova.inria. fr/~levy/talks/10enslongo/ enslongo.pdf

ARIANE 5

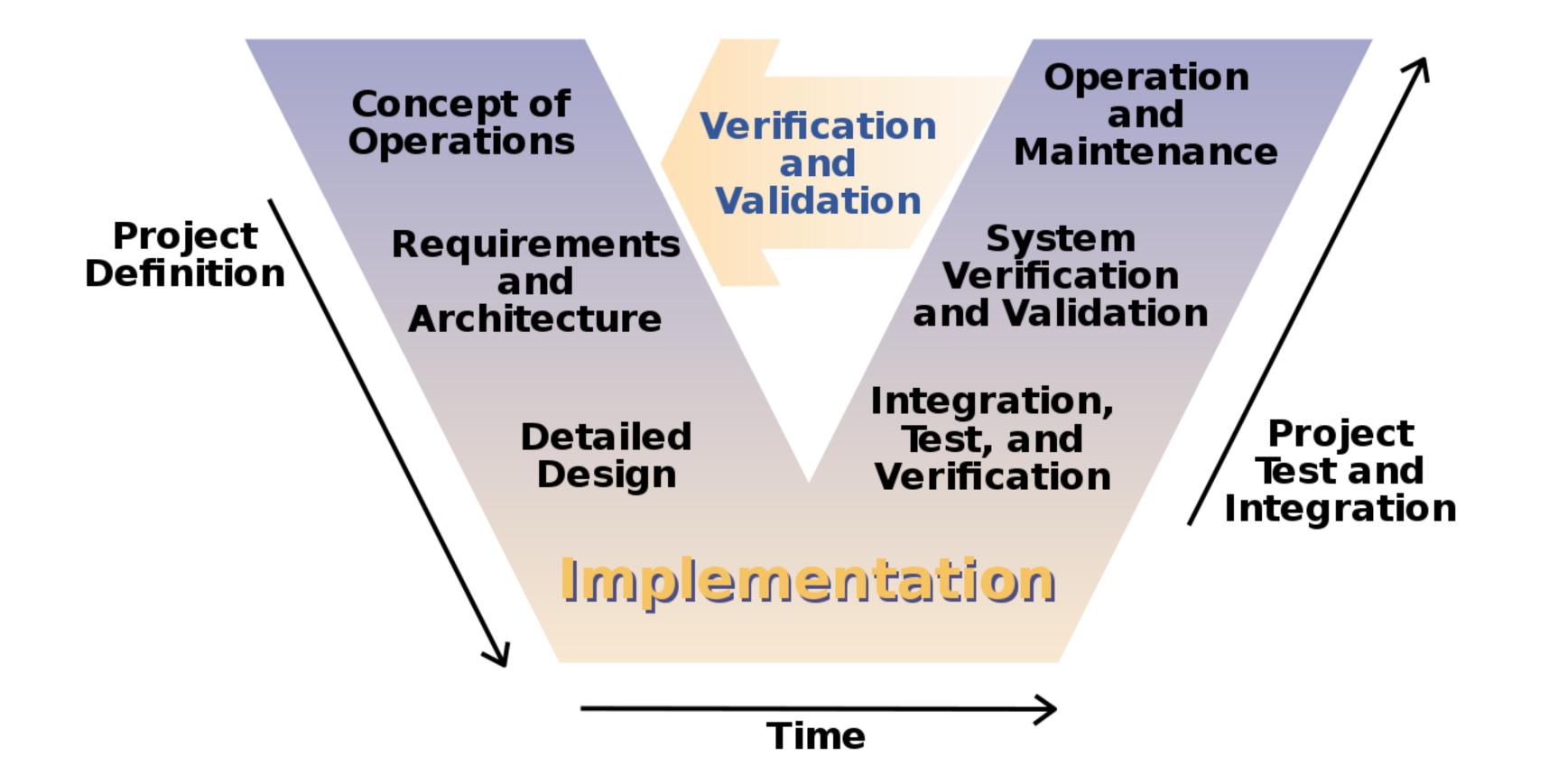
- Overflow of int16 variable
- Variable not needed dead code
- Copy pasted from Ariane 4
- Insufficient simulation tests



SOFTWARE STANDARDS

- IEC 61508: General standards for industry
- IEC 62304: Medical systems
- ISO 26262: Automotive
- IEC 61513: Nuclear Power Plants
- EN 50128: Railway Transportation
- DOC-178C: Aerospace
- NASA Safety Critical Guidelines

V-MODEL



System Development Phase (external) SW Maintenance Phase (9.2) System Requirements Specification SW Maintenance Records System Safety Requirement Specification SW Change records System Architecture Description System Safety Plan SW Requirements Phase (7.2) SW Validation Phase (7.7) SW Requirements Specification Overall SW Test Report SW Requirements Test Specification SW Validation Report SW Requirements Verification Report SW Assessment Plan SW Assessment Report MS Assessment Phase SW Architecture & Design Phase (7.3) SW Quality Assurance Plan SW Configuration Management Plan SW Verification Plan SW Validation Plan SW Walintenance Plan SW Architecture Specification SW Integration Phase (7.6) SW Design Specification SW Interface Specification SW Integration Test Report SW Integration Test Specification SW/HW Integration Test Report SW/HW Integration Test Specification SW Integration Verification Report SW Planning Phase SW Architecture & Design Verification Report SW Component Design Phase (7.4) SW Component Testing Phase (7.5) SW Component Design Specification SW ModuleTest Report SW Component Test Specification SW Source Code Verification Report SW Component Design Verification Report SW Component Implementation Phase (7.5) SW Source Code & Supporting Documentation

"It does not require that any particular lifecycle model is used, but it does require that the plan include certain ACTIVITIES and have certain ATTRIBUTES."

IEC 62304 (medical standard)

SAFETY INTEGRITY LEVEL

- SIL4: Life of many people in danger
- SIL3: Life of one person in danger
- SIL2: Severe injury possible
- SIL1: Minor injury possible

Safety Integrity Level	Probability of Dangerous Failure per hour
SIL 4	>= 10 ⁻⁹ to 10 ⁻⁸
SIL 3	$>= 10^{-8} \text{ to } 10^{-7}$
SIL 2	$>= 10^{-7}$ to 10^{-6}
SIL 1	>= 10 ⁻⁶ to 10 ⁻⁵

AEROSPACE (DO-178C)

Software Level	Effect of software anomalous behavior
Level A	Multiple loss of life, usually with loss of aircraft
Level B	The aircraft, or crew, is less capable to deal with adverse operating conditions
Level C	The aircraft, or crew, is less able to deal with unfavorable operational conditions
Level D	No significant reduction in the aircraft's level of safety
Level E	No effect on safety

DO-178C Software Levels

MEDICAL (62304)

- Class A: No injury or damage to health possible
- Class B: Non-SERIOUS INJURY is possible
- Class C: Death or SERIOUS INJURY is possible

How to control probability of failure during development?

Table A.3 – Software Architecture (7.3)

TEC	ECHNIQUE/MEASURE Ref SIL 0 SIL 1 SIL 2 SIL 3						SIL 4
1.	Defensive Programming	D.14	-	HR	HR	HR	HR
2.	Fault Detection & Diagnosis	D.26	-	R	R	HR	HR
3.	Error Correcting Codes	D.19	-	-	-	-	
4.	Error Detecting Codes	D.19	-	R	R	HR	HR
5.	Failure Assertion Programming	D.24	-	R	R	HR	HR
6.	Safety Bag Techniques	D.47	-	R	R	R	R
7.	Diverse Programming	D.16	-	R	R	HR	HR
8.	Recovery Block	D.44	-	R	R	R	R
9.	Backward Recovery	D.5	-	NR	NR	NR	NR
10.	Forward Recovery	D.30	-	NR	NR	NR	NR
11.	Retry Fault Recovery Mechanisms	D.46	-	R	R	R	R
12.	Memorising Executed Cases	D.36	-	R	R	HR	HR
13.	Artificial Intelligence – Fault Correction	D.1	-	NR	NR	NR	NR
14.	Dynamic Reconfiguration of software	D.17	-	NR	NR	NR	NR
15.	Software Error Effect Analysis	D.25	-	R	R	HR	HR
16.	Graceful Degradation	D.31	-	R	R	HR	HR
17.	Information Hiding	D.33	-	-	-	-	-
18.	Information Encapsulation	D.33	R	HR	HR	HR	HR
19.	Fully Defined Interface	D.38	HR	HR	HR	М	М
20.	Formal Methods	D.28	-	R	R	HR	HR
21.	Modelling	Table A.17	R	R	R	HR	HR
22.	Structured Methodology	D.52	R	HR	HR	HR	HR
23.	Modelling supported by computer aided design	Table	R	R	R	HR	HR

TECHNIQUE/MEASURE		Ref	SIL 0	SIL 1	SIL 2	SIL 3	SIL 4
1.	Formal Proof	D.29	1	R	R	HR	HR
2.	Static Analysis	Table A.19	ı	H	HR	HR	HR
3.	Dynamic Analysis and Testing	Table A.13	1	HR	HR	HR	HR
4.	Metrics	D.37	1	R	R	R	R
5.	Traceability	D.58	R	HR	HR	М	М
6.	Software Error Effect Analysis	D.25	-	R	R	HR	HR
7.	Test Coverage for code	Table A.21	R	HR	HR	HR	HR
8.	Functional/ Black-box Testing	Table A.14	HR	HR	HR	М	М
9.	Performance Testing	Table A.18	-	HR	HR	HR	HR
10.	Interface Testing	D.34	HR	HR	HR	HR	HR

Requirements:

- 1) For software Safety Integrity Levels 3 and 4, the approved combination of techniques is 3, 5, 7, 8 and one from 1, 2 or 6.
- For Software Safety Integrity Level 1 and 2, the approved combinations of techniques is 5 together with one from 2, 3 or 8.
- NOTE 1 Techniques/measures 1, 2, 4, 5, 6 and 7 are for verification activities.
- NOTE 2 Techniques/measures 3, 8, 9 and 10 are for testing activities.

Table A.12 – Coding Standards

TEC	TECHNIQUE/MEASURE		SIL 0	SIL 1	SIL 2	SIL 3	SIL 4
1.	Coding Standard	D.15	HR	HR	HR	М	M
2.	Coding Style Guide	D.15	HR	HR	HR	HR	HR
3.	No Dynamic Objects	D.15	-	R	R	HR	HR
4.	No Dynamic Variables	D.15	-	R	R	HR	HR
5.	Limited Use of Pointers	D.15	-	R	R	R	R
6.	Limited Use of Recursion	D.15	-	R	R	HR	HR
7.	No Unconditional Jumps	D.15	-	HR	HR	HR	HR
8.	Limited size and complexity of Functions, Subroutines and Methods	D.38	HR	HR	HR	HR	HR
9.	Entry/Exit Point strategy for Functions, Subroutines and Methods	D.38	R	HR	HR	HR	HR
9.	Limited number of subroutine parameters	D.38	R	R	R	R	R
10.	Limited use of Global Variables	D.38	HR	HR	HR	М	М

Requirement:

1) It is accepted that techniques 3, 4 and 5 may be present as part of a validated compiler or translator.

TEC	CHNIQUE/MEASURE	Ref	SIL 0	SIL 1	SIL 2	SIL 3	SIL 4
1.	ADA	D.54	R	HR	HR	HR	HR
2.	MODULA-2	D.54	R	HR	HR	HR	HR
3.	PASCAL	D.54	R	HR	HR	HR	HR
4.	C or C++	D.54 D.35	R	R	R	R	R
5.	PL/M	D.54	R	R	R	NR	NR
6.	BASIC	D.54	R	NR	NR	NR	NR
7.	Assembler	D.54	R	R	R	R	R
8.	C#	D.54 D.35	R	R	R	R	R
9.	JAVA	D.54 D.35	R	R	R	R	R
10.	Statement List	D.54	R	R	R	R	R

l = . .

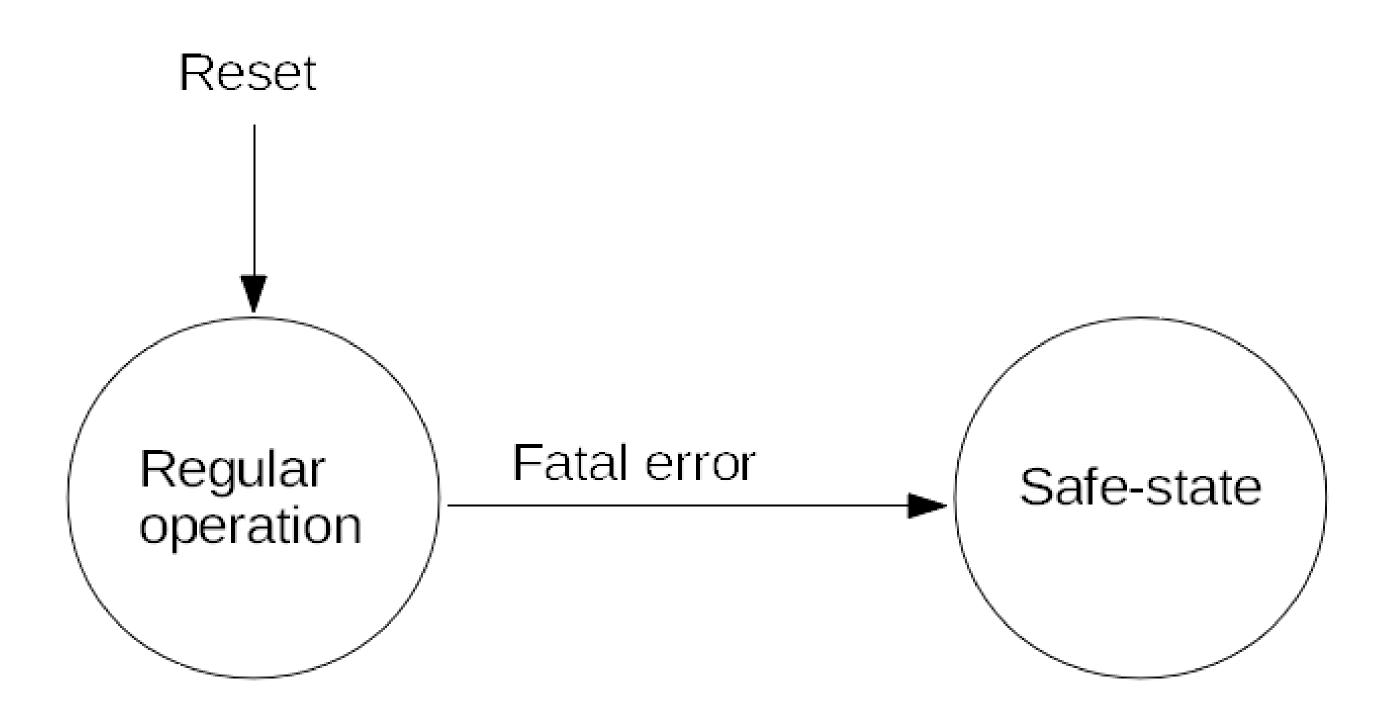
SAFETY AT SYSTEM LEVEL?

- You cannot finish implementation first and then introduce safety.
- You cannot implement safe modules and expect resulting system to be safe
- You must care about safety from the start

RISK ANALYSIS

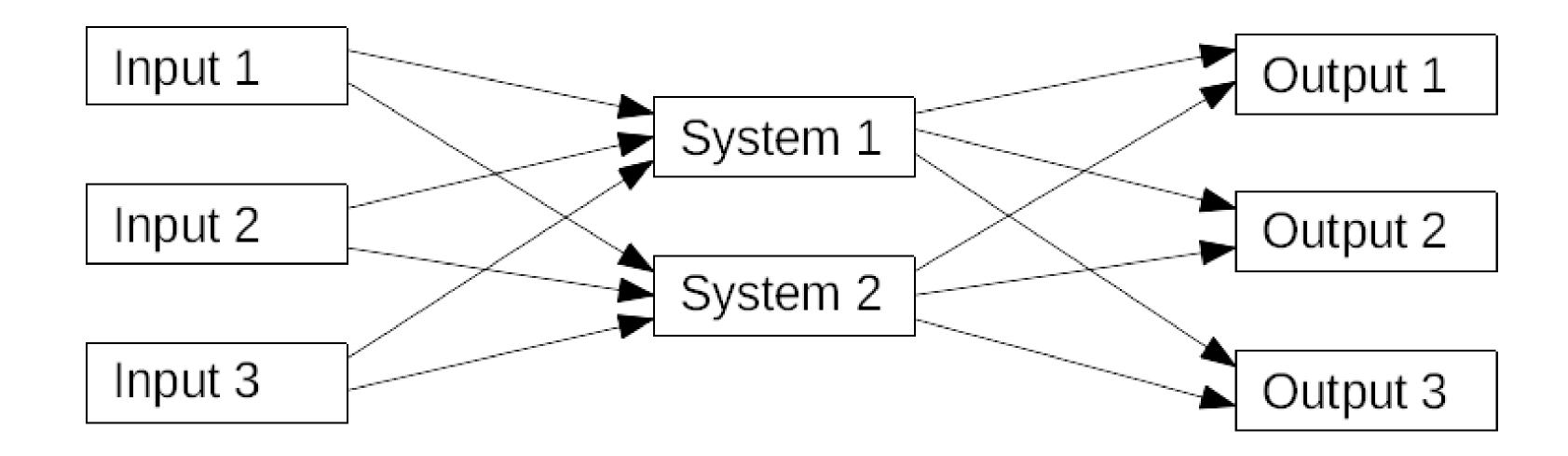
RISK ASSESSMENT MATRIX								
SEVERITY PROBABILITY	Catastrophic (1)	Critical (2)	Marginal (3)	Negligible (4)				
Frequent (A)	High	High	Serious	Medium				
Probable (B)	High	High	Serious	Medium				
Occasional (C)	High	Serious	Medium	Low				
Remote (D)	Serious	Medium	Medium	Low				
Improbable (E)	Medium	Medium	Medium	Low				
Eliminated (F)	Eliminated							

SAFE STATE

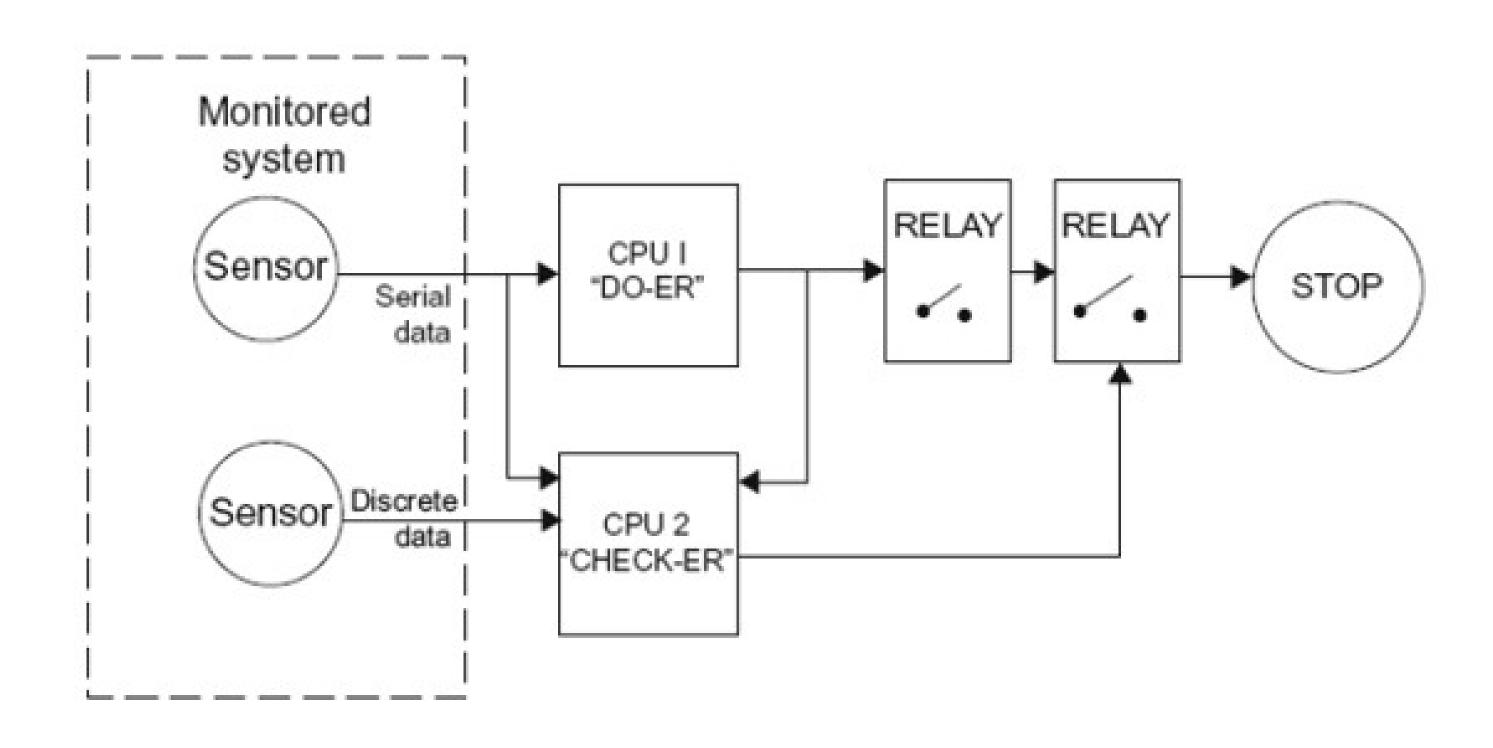




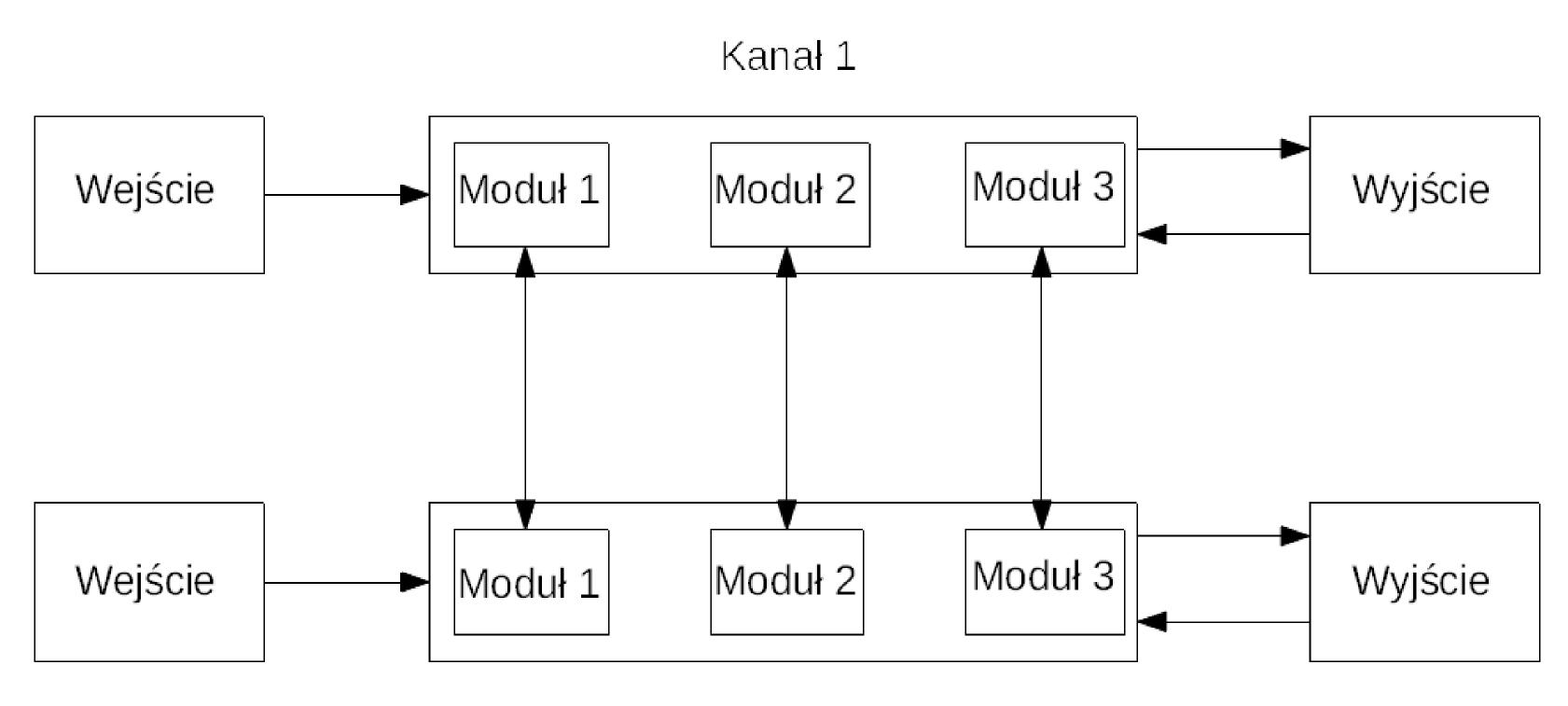
REDUNDANCY



SUPERVISOR CPU

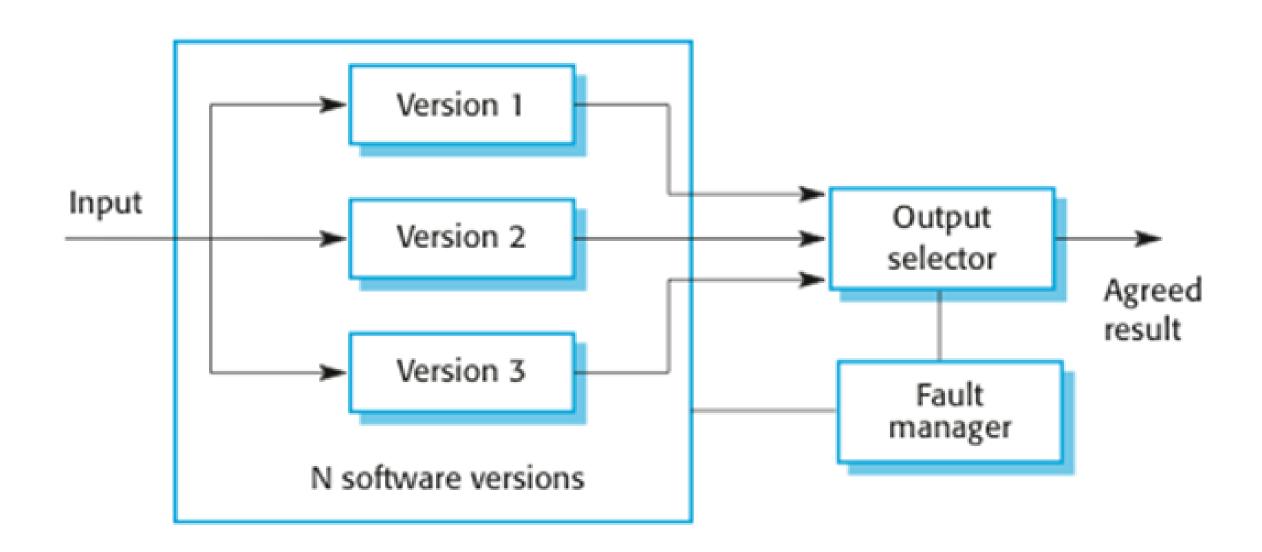


INDEPENDENT CHANNELS



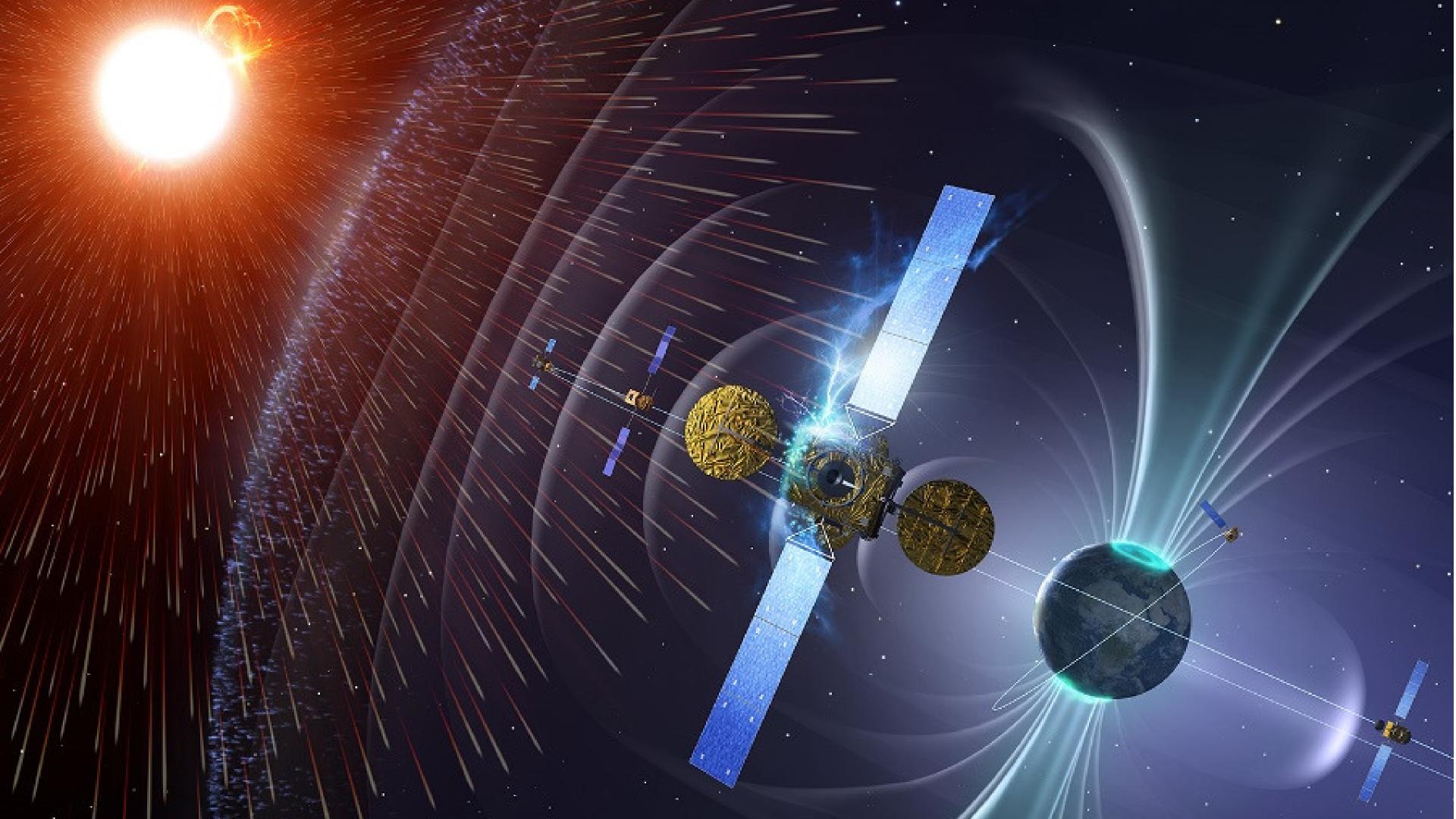
Kanał 2

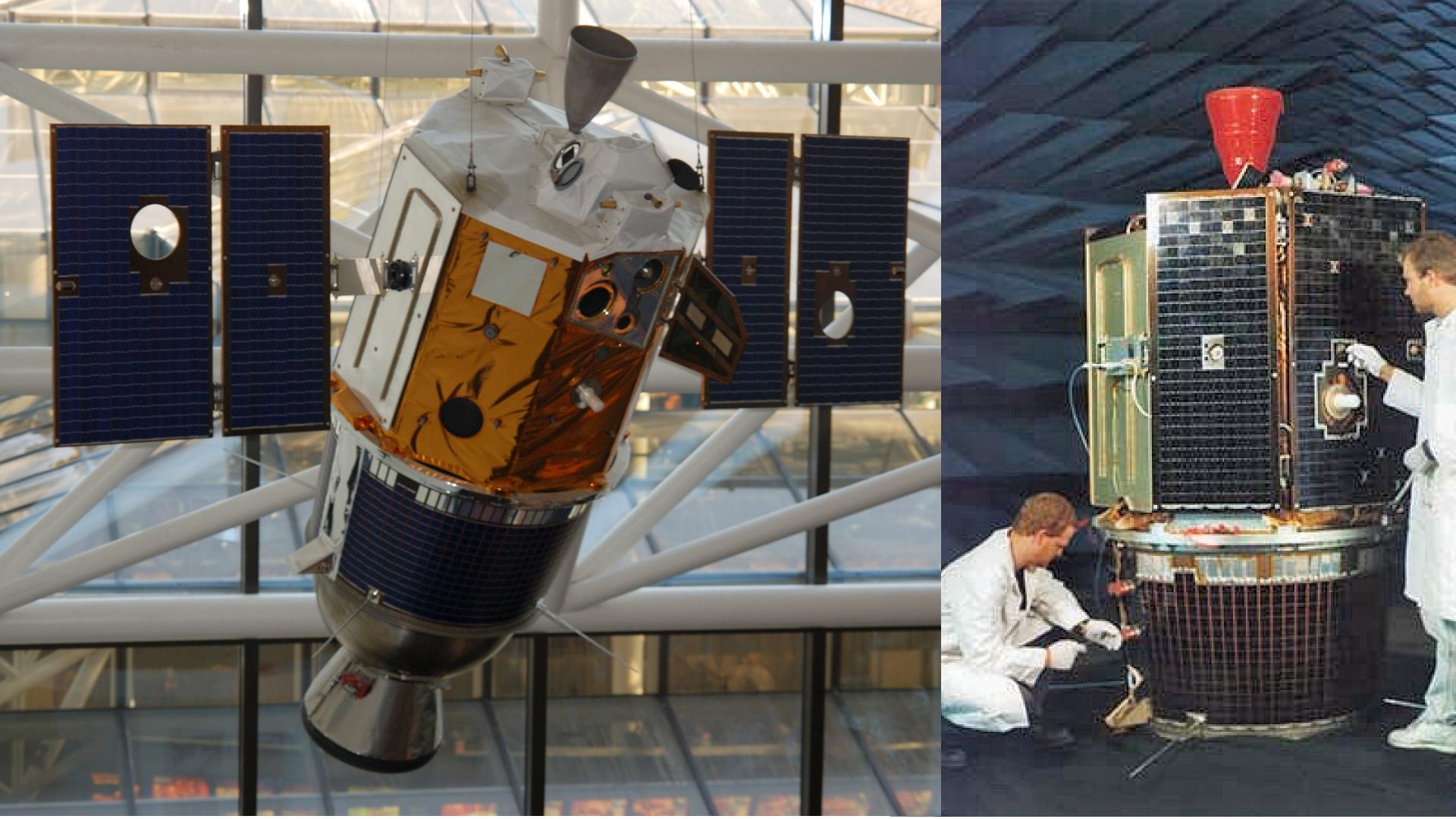
VOTING SYSTEM

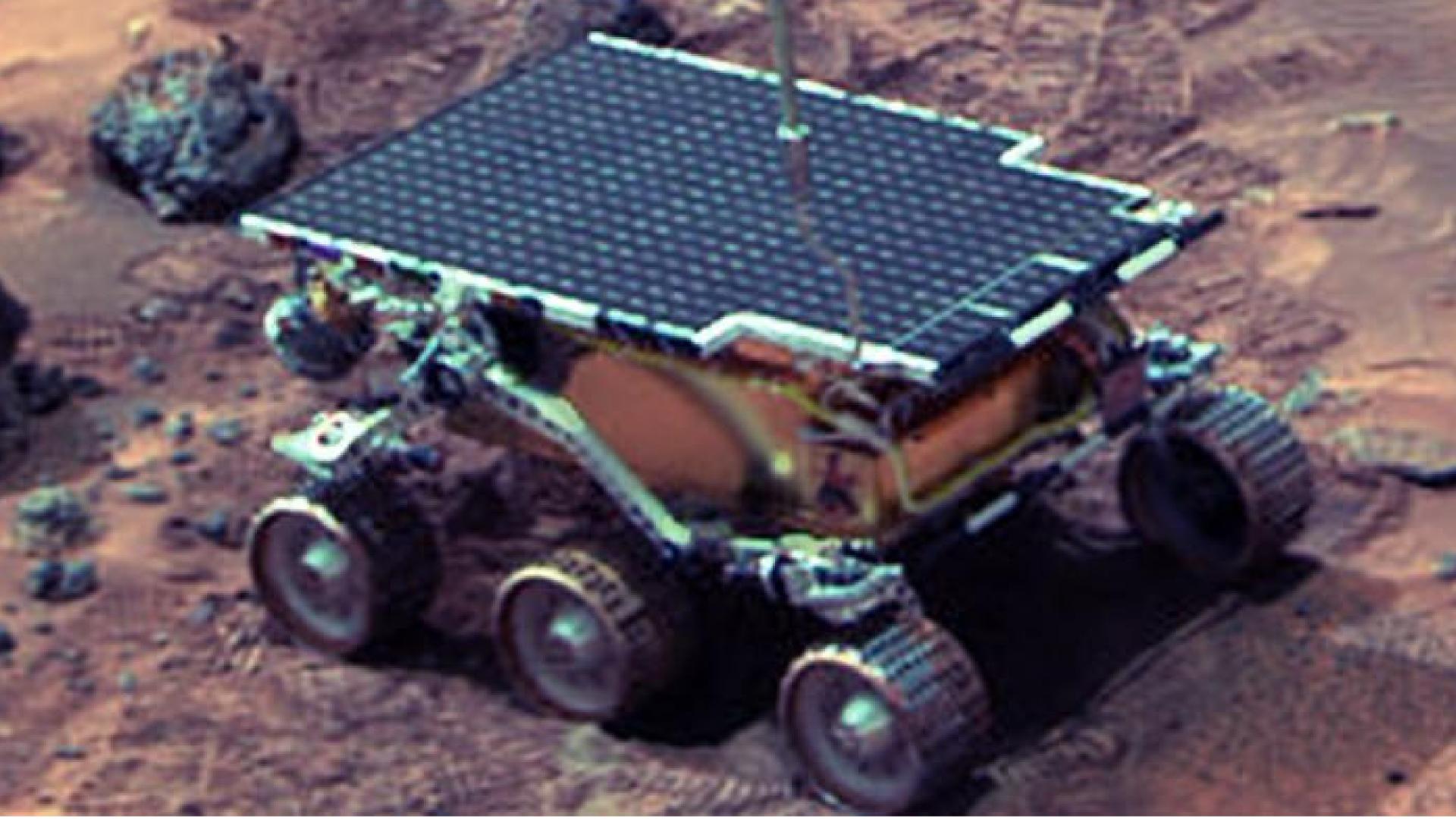


DIVERSE PROGRAMING

- Channels implemented by independent teams
- Teams don't exchange information
- Teams share documentation
- Reducing risk of the same software errors
- Possible ways of diversification: hardware, programming languages, techniques



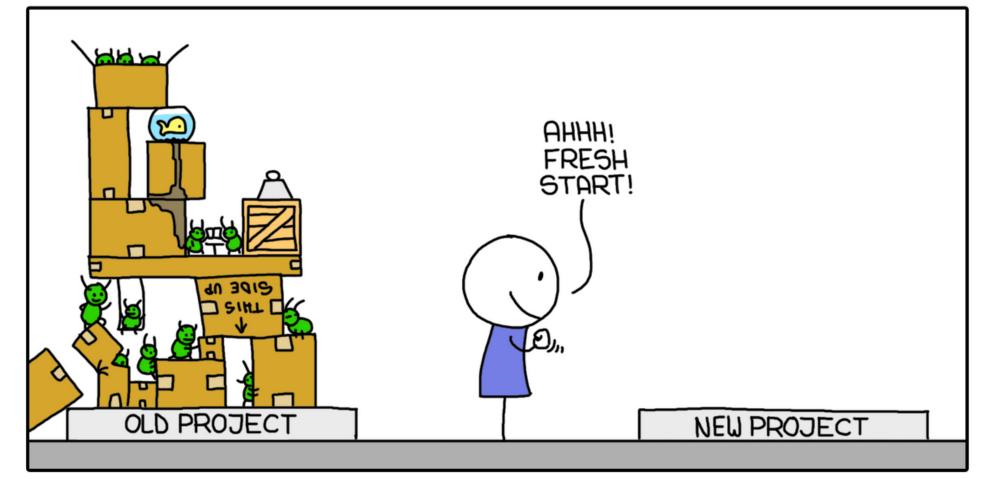


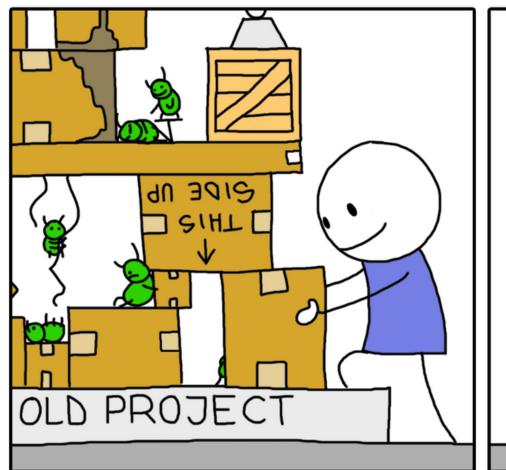


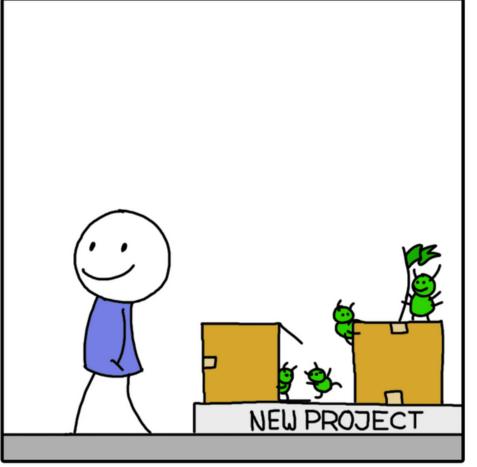
SANITY CHECKS

- RAM tests
- Non-volatile Memory tests
- CPU Tests registers and instructions
- Power supply tests
- Sensor tests
- Clock system tests

CODE REUSE







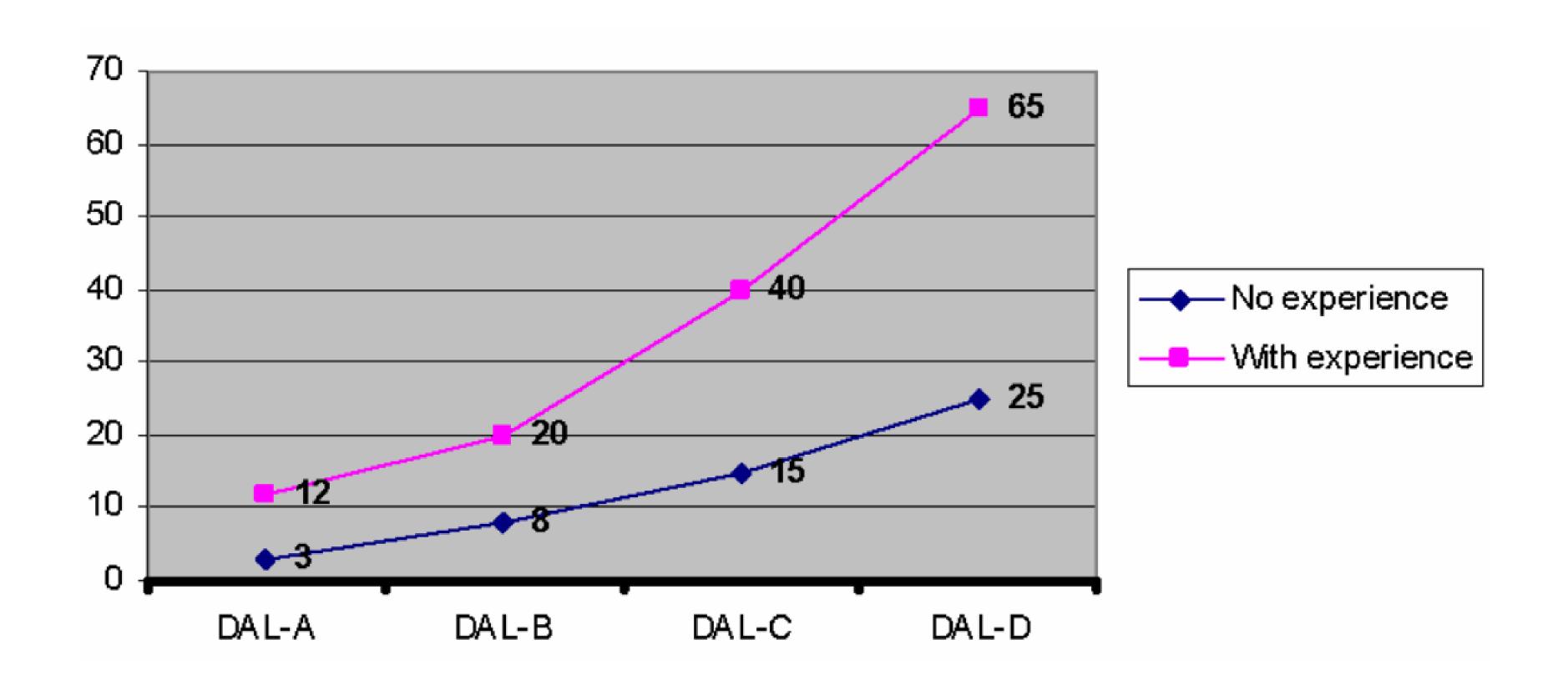
MONKEYUSER.COM

SOUP - SOFTWARE OF UNKNOWN PROVENANCE

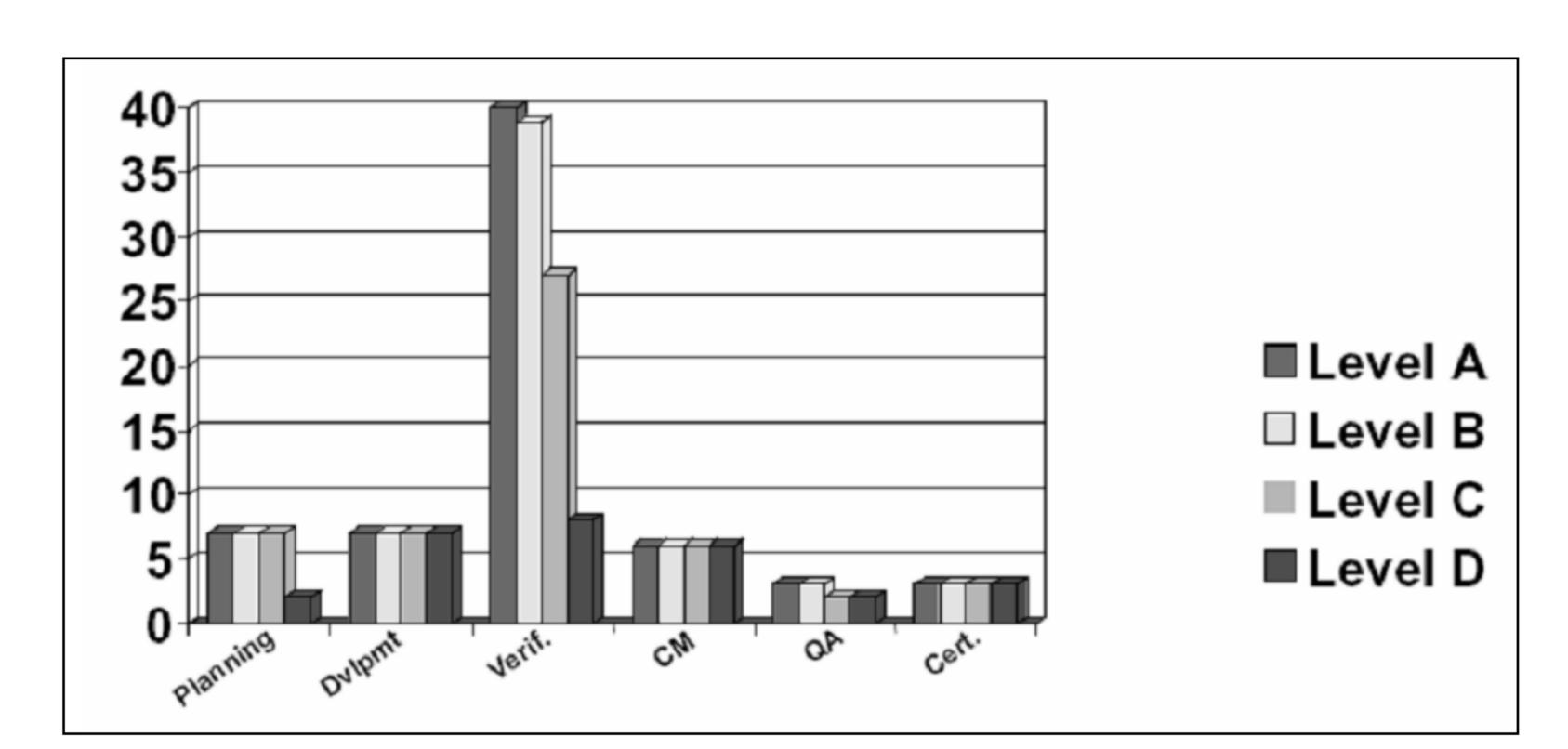
- Insufficient documentation
- No risk assesment
- Unknown development and testing procedures
- Dedicated commercial libraries turn out to be cheaper



LINES OF CODE PER HOUR



DISTRIBUTION OF ACTIVITIES IN SAFETYCRITICAL SYSTEM



SHOULD WE BE AFRAID OF REGULATIONS?



Read more:

https://ucgosu.pl/safety-critical-eng/



THANK YOU FOR YOUR ATTENTION!